

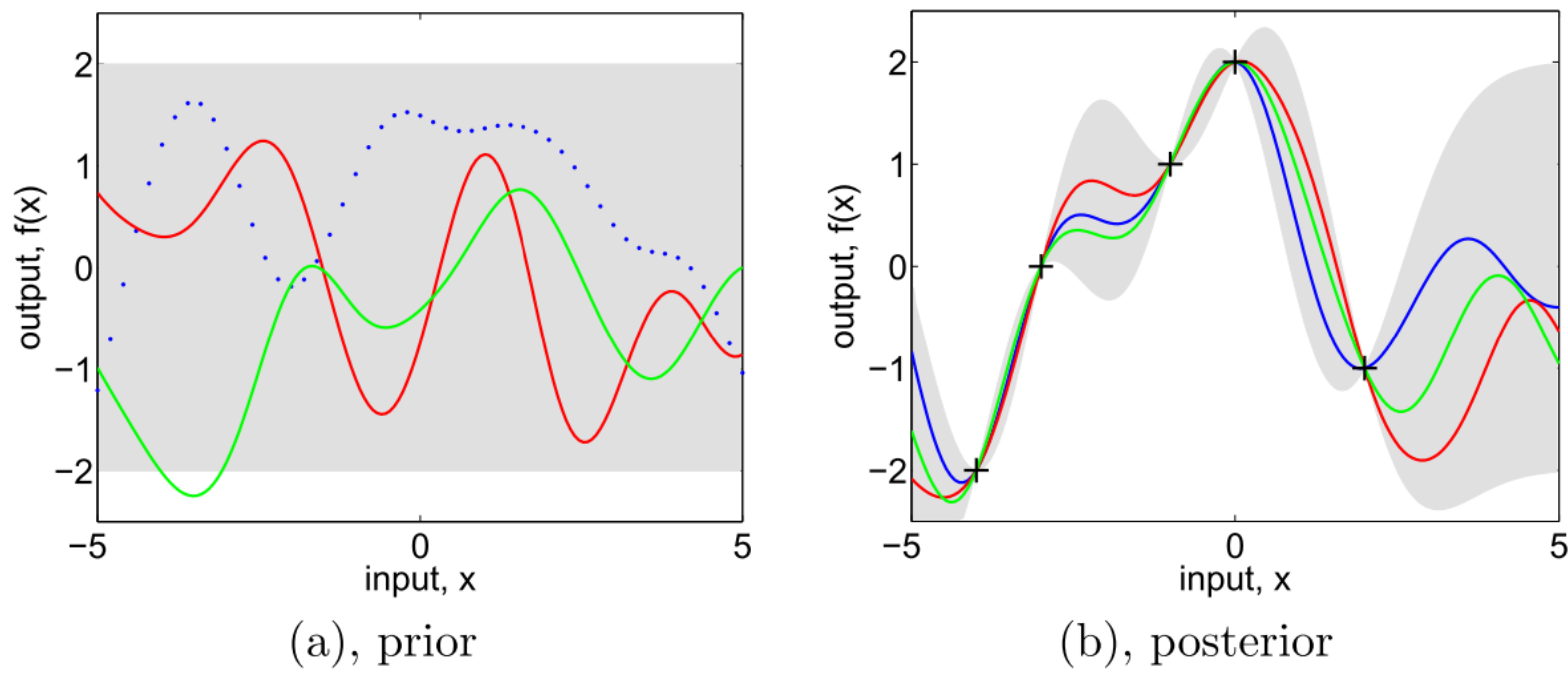
High-fidelity transfer of functional priors for wide Bayesian neural networks by learning activations

Problem: Real priors are not nice

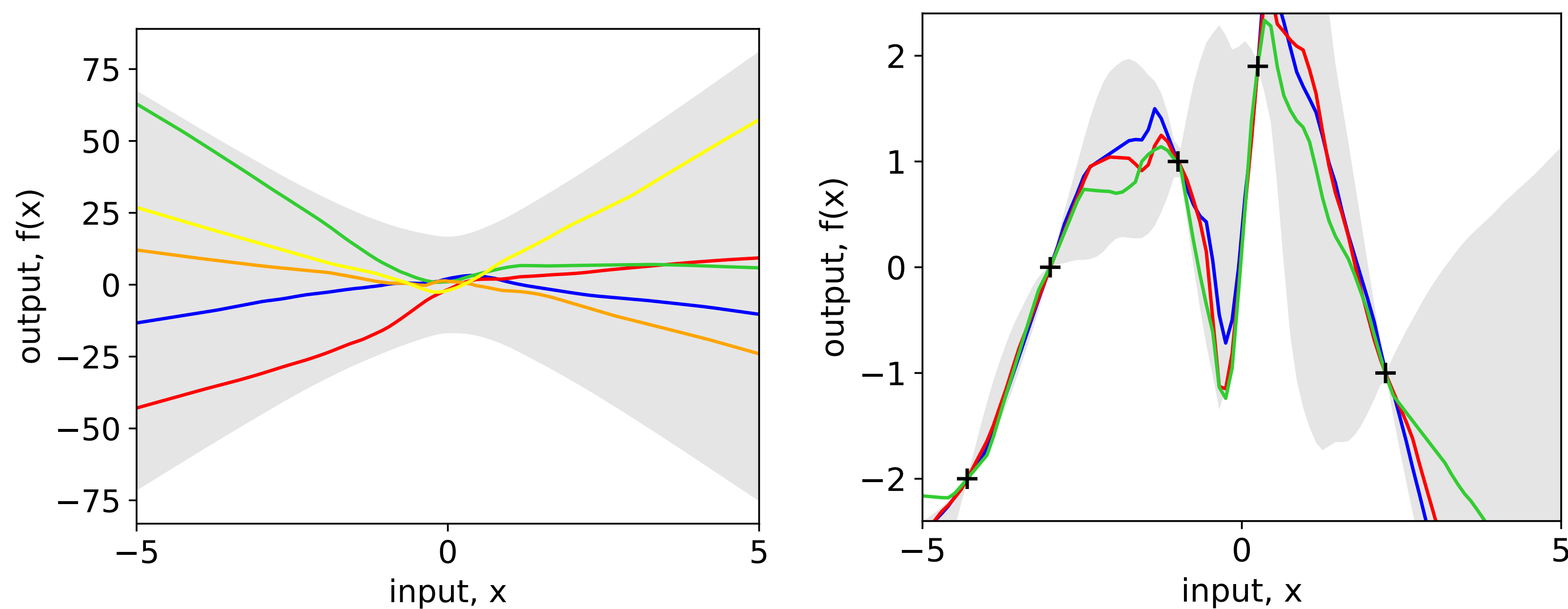
Recap:

prior $p(w, b)$ + likelihood $p(y|w, b, x)$ + data $\{x, y\}$
 \rightarrow posterior $p(w, b|\{x, y\})$

Expectations



Real-world



Adapted from *GPs for ML* (Carl Edward Rasmussen, Christopher K. I. Williams, 2006)

function-space view \rightarrow smoothness and interpretability

prior $p(f^l)$ + likelihood $p(y|f^l, x)$ + data $\{x, y\}$

How to find such function-space priors?

Gaussian Processes:

$$f(x) \sim \text{GP}(m(x), \kappa(x, x'))$$

where $m(x)$ is the mean function and $\kappa(x, x')$ is the kernel defining properties of $f(x)$. (kernel specification)

Wide BNNs are GPs!

$$p(f^l(x)) \xrightarrow{\text{width} \rightarrow \infty} \mathcal{N}(\mu(x), \sigma^2(x)),$$

$$\text{Cov}(f^l(x), f^l(x')) = \sigma_b^2 + \sigma_w^2 \mathbb{E}_{w_0, b}[\phi(w_0 x + b^0)\phi(w_0 x' + b^0)],$$

BNN corresponds to a GP(\cdot, κ): $\kappa_f^l(x, x') = \text{Cov}(f^l(x), f^l(x'))$

- find κ_f^l given f^l : Easy
- identify f^l given κ_f^l : Hard

Enforcing function-space GP Priors in BNNs

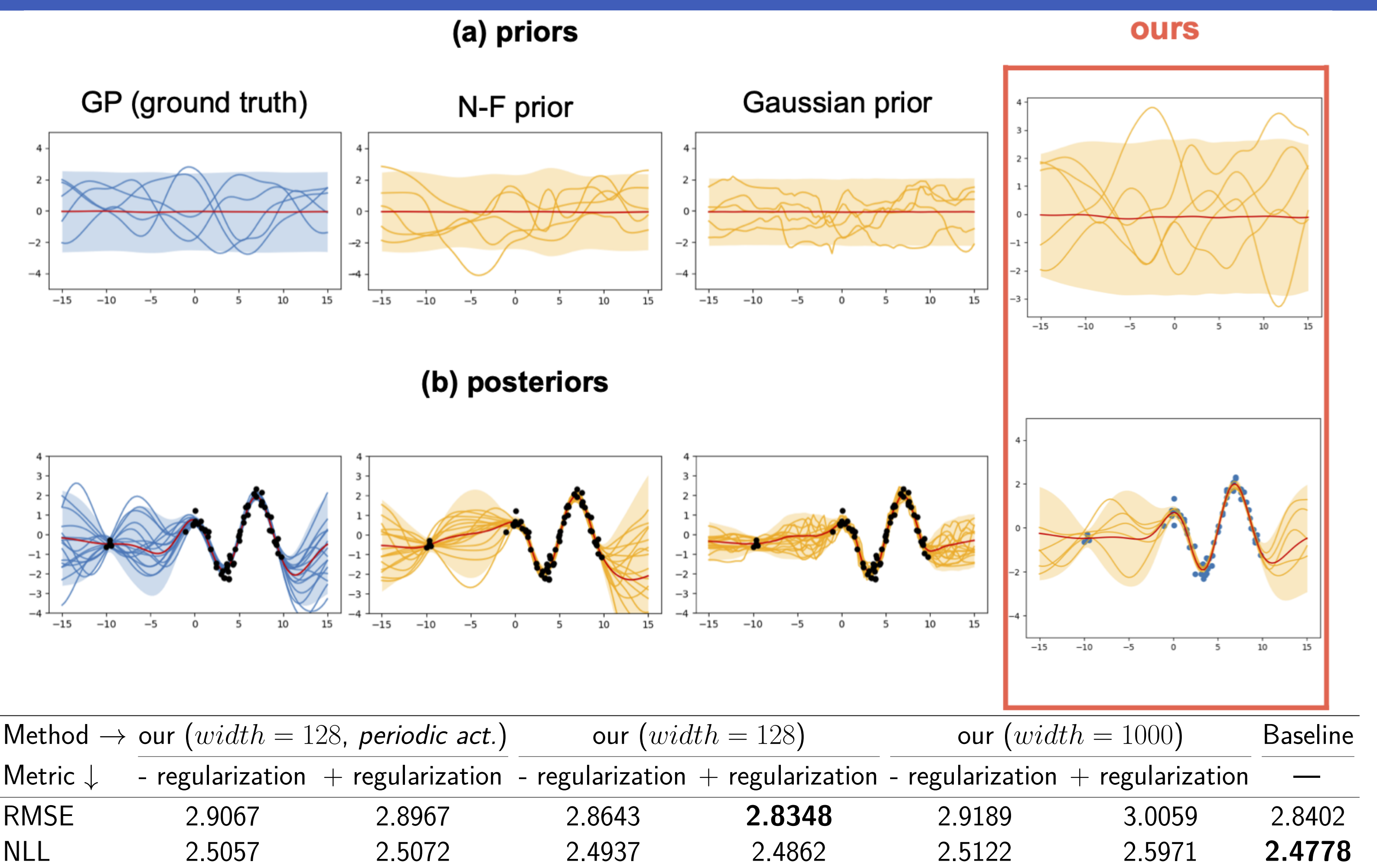
- Reparameterize priors and activation:
 $p(w, b|\lambda) = N(w|0, \text{diag}(\sigma_w))N(b|0, \text{diag}(\sigma_b)), \phi(\cdot|\eta)$

e.g. periodic activation for enforcing stationarity:
 $\phi(x|\eta) = \sum_{i=1}^K A_i \cos(2\pi\psi_i x) + \sum_{j=1}^K A_j \sin(2\pi\psi_j x)$,
 where $\eta = \{\psi_i, A_i, \psi_j, A_j\}$.

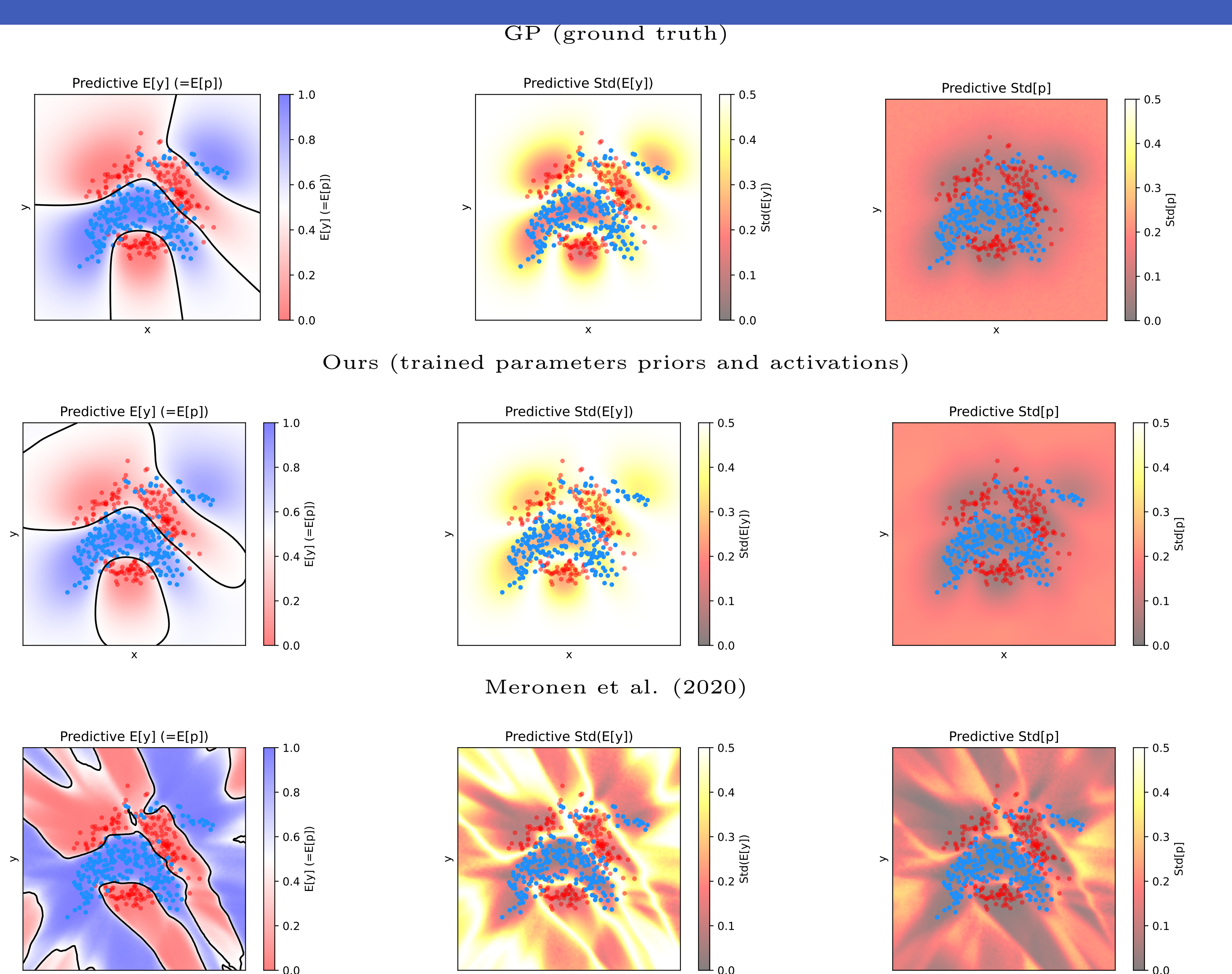
- $\lambda^* = \text{argmin}_{\lambda} \frac{1}{S} \sum_{X \sim p_X} D(p_{nn}(f^l(X|\lambda)), p_{gp}(f^l(X)))$,
 where $\lambda = \{\sigma_w, \sigma_b, \eta\}$

- Closed-form 2-Wasserstein divergence between two Gaussians:
 $D = \|\mu_1 - \mu_2\|_2^2 + \text{Tr}(\Sigma_1 + \Sigma_2 - 2\sqrt{\Sigma_1 \Sigma_2 \Sigma_1})$

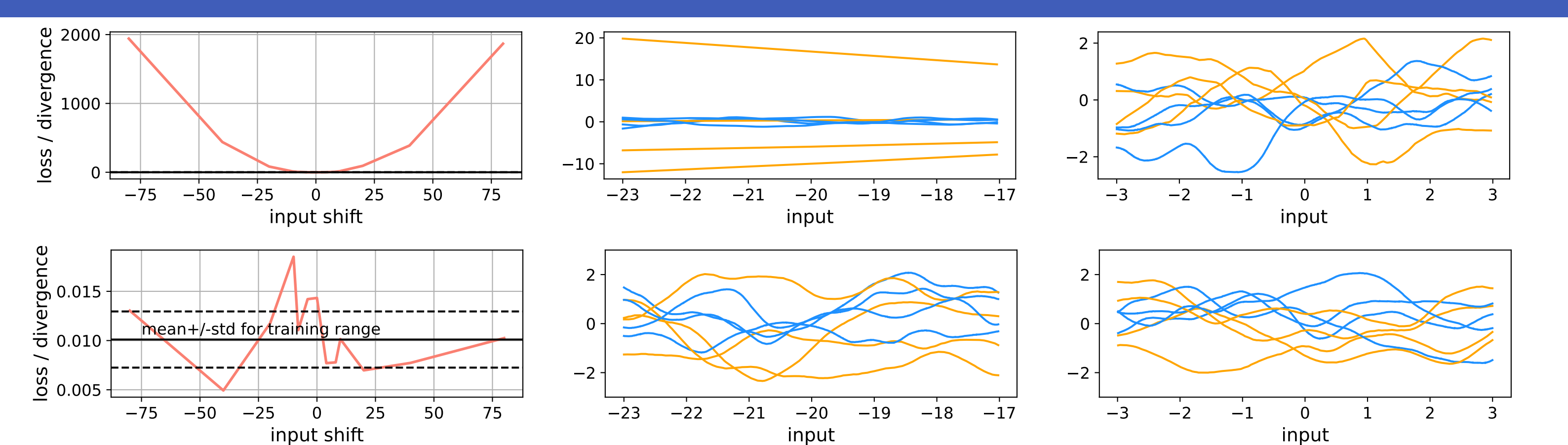
Regression



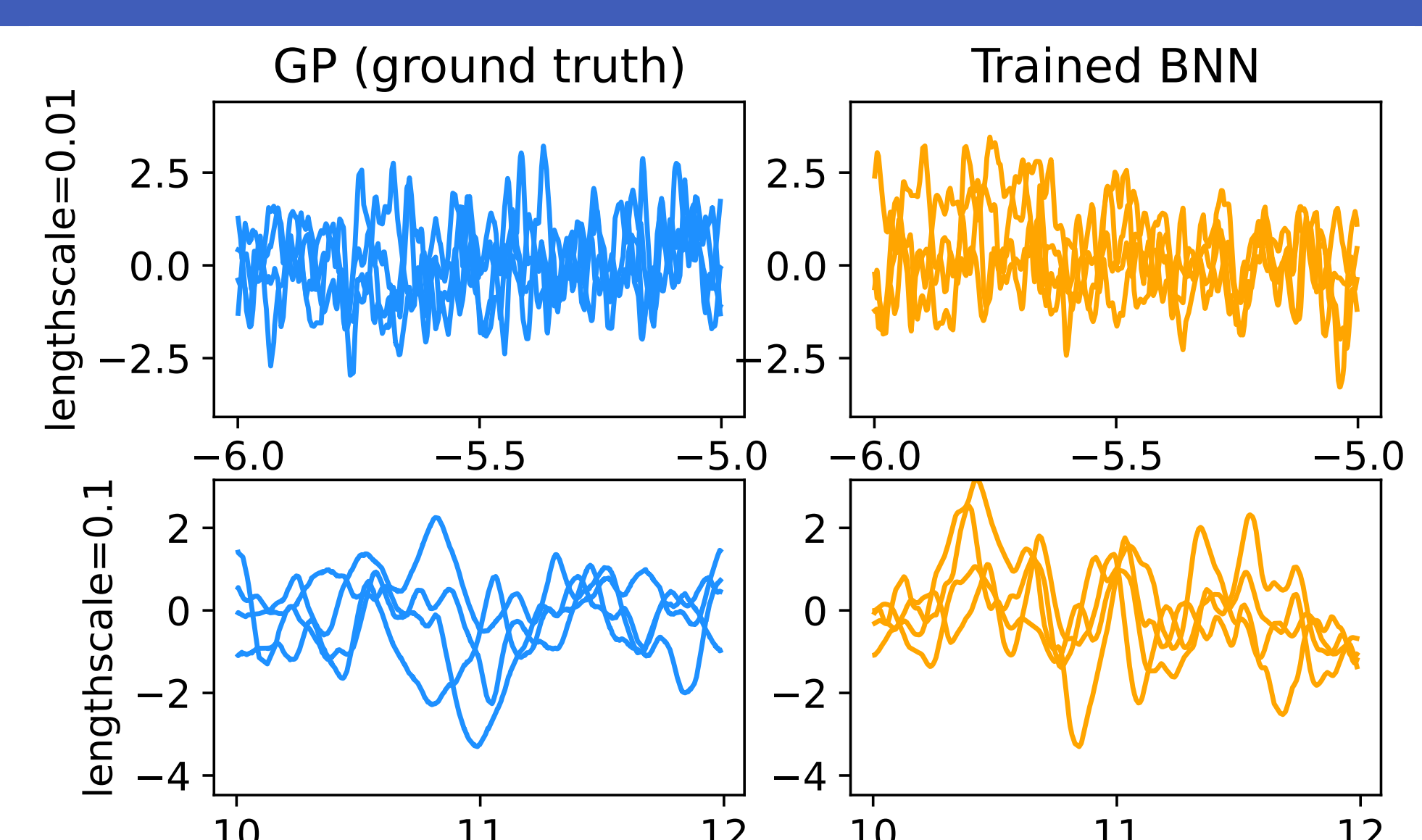
Classification



Stationarity outside training range



Conditioning



Future work

- Scaling to multi-dimensional outputs
- Creating plug-and-play GP-like layers for standard NNs
- Improving Bayesian deep learning approaches by enforcing GP-like behaviour (and posterior) on a specific layer of a NN

