

Revisiting the Equivalence of Bayesian Neural Networks and Gaussian Processes:

On the Importance of Learning Activations

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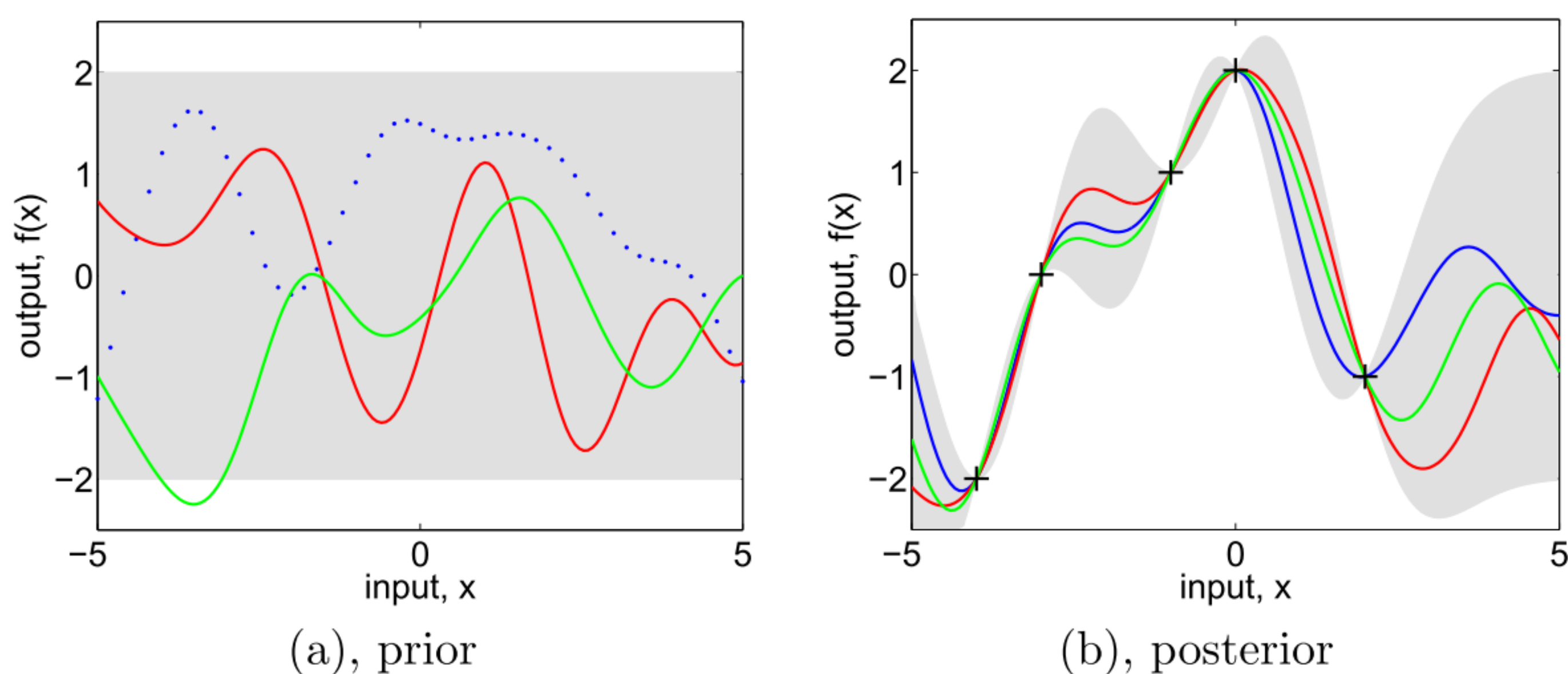
tl;dr: How to effectively transfer function-space priors into BNNs?

Problem: Real priors are not nice

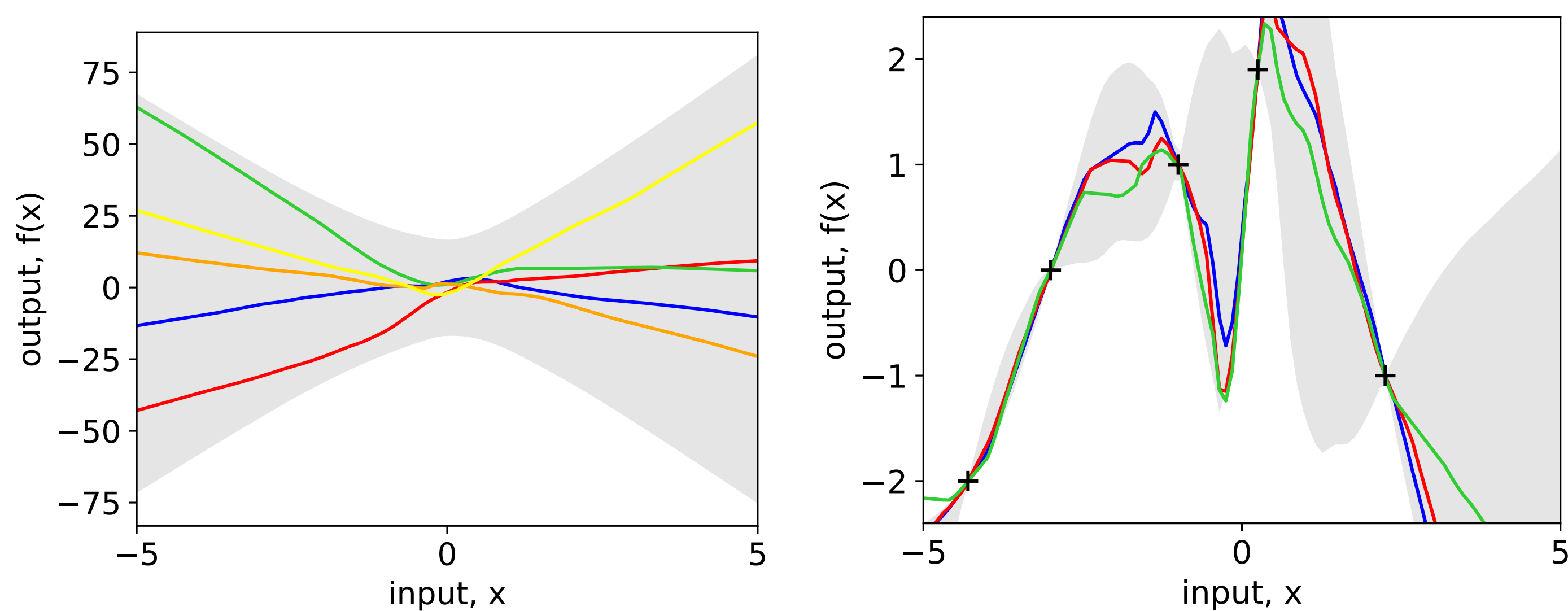
Recap:

prior $p(w, b)$ + likelihood $p(y|w, b, x)$ + data $\{x, y\}$
→ posterior $p(w, b|\{x, y\})$

Expectations



Real-world BNNs



Adapted from *GPs for ML* (Carl Edward Rasmussen, Christopher K. I. Williams, 2006)

function-space view → smoothness and interpretability

prior $p(f^l)$ + likelihood $p(y|f^l, x)$ + data $\{x, y\}$
→ posterior $p(f^l|\{x, y\})$

How to find such function-space priors?

Wide BNNs are GPs!

Gaussian Processes:

$$f(x) \sim \text{GP}(m(x), \kappa(x, x')),$$

where the **kernel** $\kappa(x, x')$ governs the properties of $f(x)$

BNN corresponds to a GP $(\cdot, \kappa)$: $\kappa_f^l(x, x') = \text{Cov}(f^l(x), f^l(x'))$,
where: Cov is the covariance from a BNN f^l :

$$p(f^l(x)) \xrightarrow{\text{width} \rightarrow \infty} \mathcal{N}(\mu(x), \sigma^2(x)),$$

$$\text{Cov}(f^l(x), f^l(x')) = \sigma_b^2 + \sigma_w^2 \mathbb{E}_{w_0, b}[\phi(w_0 x + b^0) \phi(w_0 x' + b^0)],$$

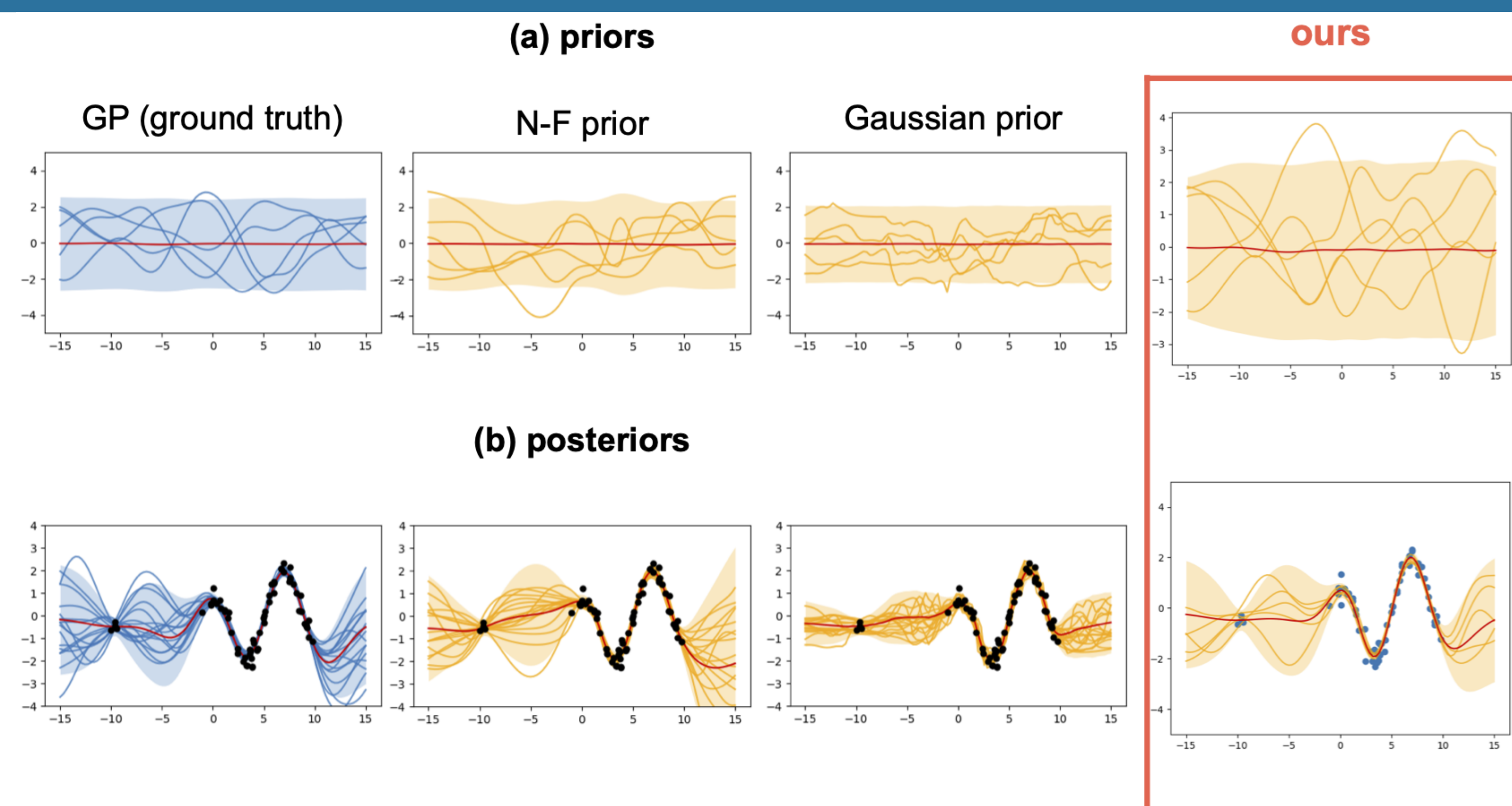
- **Easy:** BNN → GP (find κ_f^l given f^l)
- **Problem:** GP → BNN (identify f^l given κ_f^l)

Enforcing function-space GP Priors in BNNs

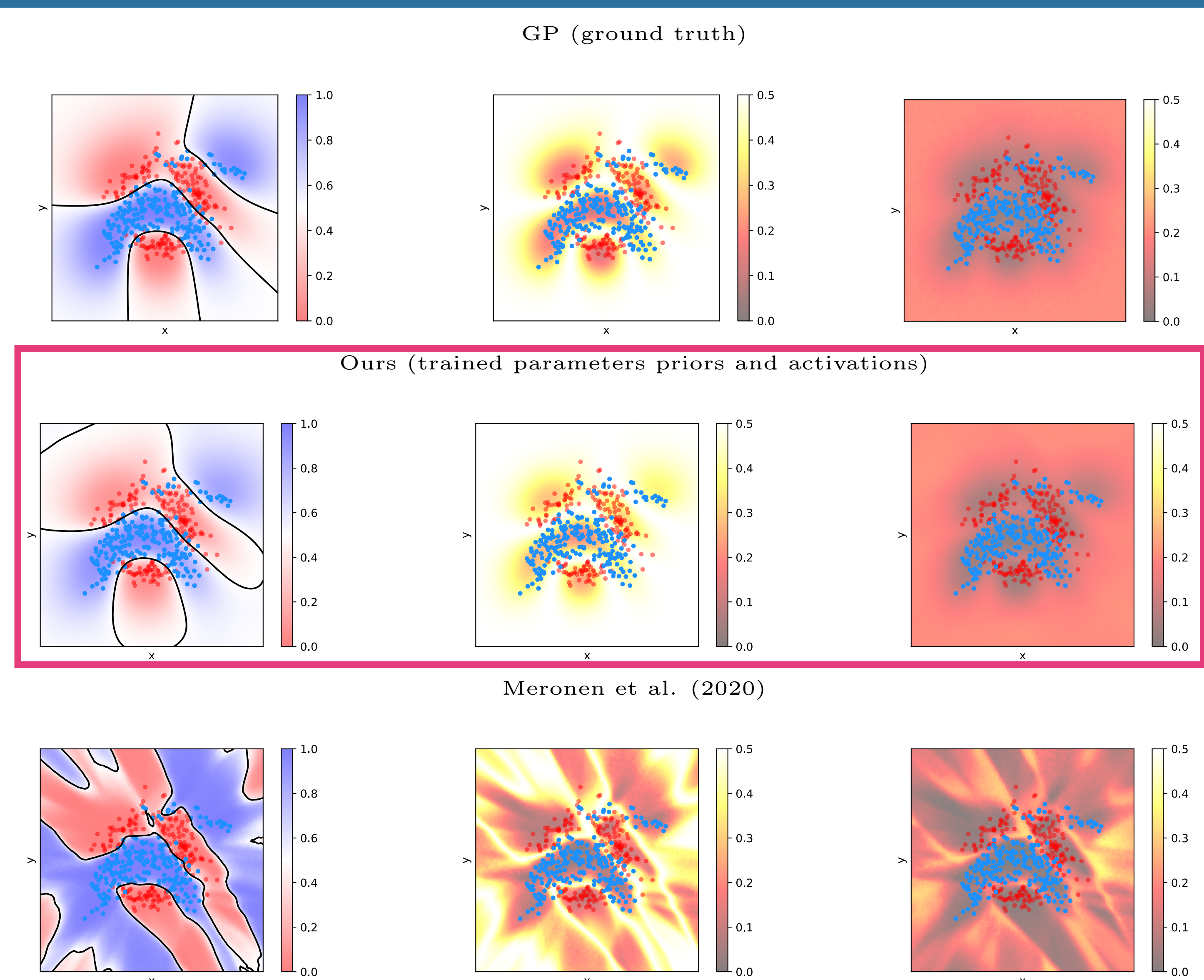
In three simple steps:

1. Reparameterize priors and **activation**:
 $p(w, b|\lambda) = N(w|0, \text{diag}(\sigma_w))N(b|0, \text{diag}(\sigma_b)), \phi(\cdot|\eta)$
2. Optimize a distributional **divergence** between a GP and a BNN:
 $\lambda^* = \arg\min_{\lambda} \frac{1}{S} \sum_{X \sim p_X} D(p_{nn}(f^l(X|\lambda)), p_{gp}(f^l(X))),$ where $\lambda = \{\sigma_w, \sigma_b, \eta\}$
3. Use **closed-form 2-Wasserstein** divergence between two Gaussians:
 $D = \|\mu_1 - \mu_2\|_2^2 + \text{Tr}(\Sigma_1 + \Sigma_2 - 2\sqrt{\Sigma_1 \Sigma_2 \sqrt{\Sigma_1}})$

Regression



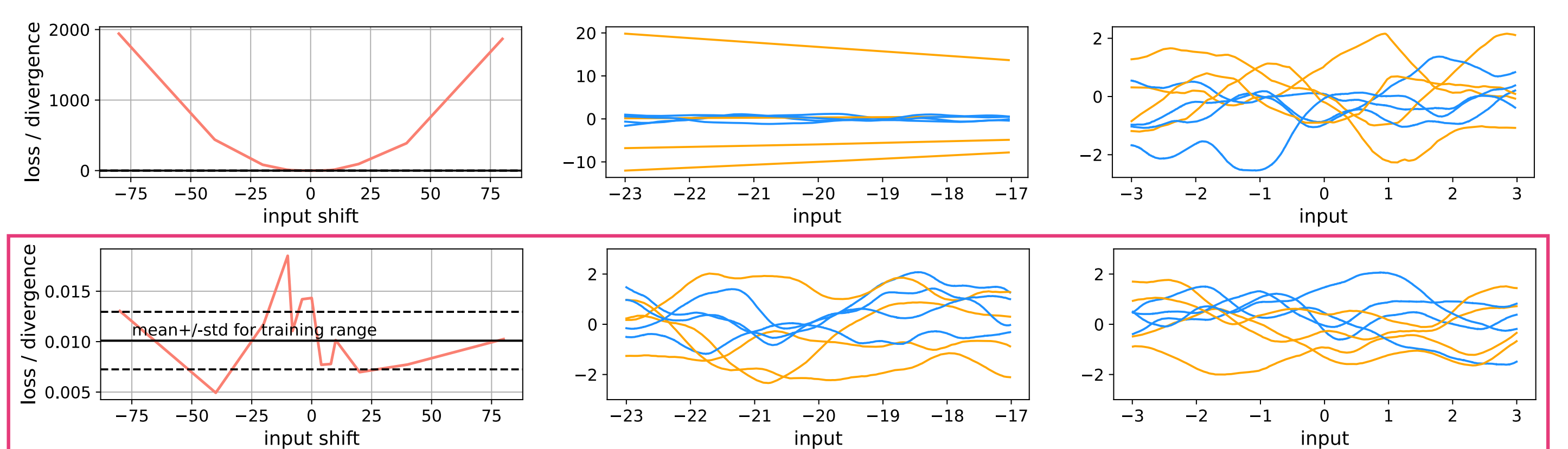
Classification



Stationarity outside training range

By default the BNNs are not preserving the stationarity of GPs.

However: **appropriate activation (periodic)** → stationarity!



$$\phi(x|\eta) = \sum_{i=1}^K A_i \cos(2\pi\psi_i x) + \sum_{j=1}^K A_j \sin(2\pi\psi_j x), \text{ where } \eta = \{\psi_i, A_i, \psi_j, A_j\}$$

Takeaway

- **Function-space priors** improve BNNs
- **Learnable activations** enable better fits
- **Inductive biases** (e.g. stationarity) can be enforced by tailored activations
- **Model selection** is enabled by conditioning activations
- **Optimal transport** with **closed-form 2-W divergence** helps optimization

